2090-Series Motor/Actuator Cables

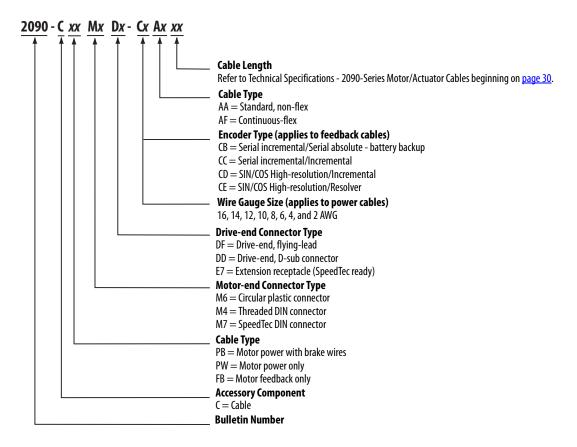
A wide variety of motor/actuator cables with rugged DIN connectors are available for connecting your motion control system. Standard (non-flex) motor power and feedback cables are available for all Allen-Bradley servo motors and actuators. Continuous-flex rated cables, intended for moving applications, are also available. Continuous-flex extension and standard (non-flex) transition cables are also available for your applications that require them.

IMPORTANT	All flying-lead feedback cables require breakout components or connector kits for drive-end terminations. Refer to Breakout Components and Connector Kits beginning on <u>page 65</u> for catalog numbers and descriptions.
IMPORTANT	Standard (non-flex) cables have a regular maintenance and installation bend radius of 10 times the cable diameter. For flexing applications, continuous-flex cables have an operational bend radius of 12 times the cable diameter.

Catalog Numbers - 2090-Series Motor/Actuator Cable

Catalog numbers consist of various characters, each of which identifies a specific option for that component. Use the catalog numbering charts below to understand the configuration of your component. For questions regarding product availability, contact your Allen-Bradley distributor.

Motor Power/Brake, Feedback, and Extension Cables



2090-Series Motor/Actuator Cables Overview

Feedback Cable Descriptions (standard, non-flex)

Standard Cable	Description	Cable Configuration	Motor/Actuator Connector	
Cat. No.	Description	Motor/Acutator End Drive End		
2090-CFBM7DF-CEAAxx	Drive-end flying-leads (DF) High-resolution or resolver applications (CE)	THE REPORT OF THE PERSON OF TH	SpeedTec DIN	
2090-CFBM7DD-CEAAxx	 Drive-end 15-pin connector (DD) High-resolution or resolver applications (CE) 		(M7)	
2090-XXNFMF-Sxx	Drive-end flying-leads High-resolution or incremental applications		Threaded DIN	
2090-CFBM4E2-CATR	Drive-end bayonet (E2), transition (TR) cable (1) Motor-end threaded DIN (M4) All feedback types (CA)		(M4)	
2090-CFBM6DF-CBAAxx	Drive-end flying-leads (DF) High-resolution, battery backup or Incremental applications (CB)	38	Circular Plastic	
2090-CFBM6DD-CCAAxx	Drive-end 15-pin connector (DD) Incremental applications only (CC)	36 RR	(M6)	
2090-DANFCT-Sxx	Drive-end 20-pin connector High-resolution applications	THE SECOND SECTION OF THE SECOND SECTION OF THE SECOND SEC	Rectangular Plastic	

⁽¹⁾ Threaded DIN connector (motor end) and bayonet connector for 2090-XXNFMP-Sxx cable. Refer to 2090-Series Motor Power and Feedback Transition Cables on page 17.

Feedback Cable Descriptions (continuous-flex)

Continuous-flex Cable	Description	Cable Configuration	Motor/Actuator Connector	
Cat. No.	Description	Motor/Acutator End Drive End		
2090-CFBM7DF-CDAFxx	Drive-end flying-leads (DF) High-resolution or incremental applications (CD)	MMMMM 38		
2090-CFBM7DF-CEAFxx	Drive-end flying-leads (DF) High-resolution or resolver applications (CE)	MMMMMI 98	SpeedTec DIN	
2090-CFBM7DD-CEAFxx	Drive-end 15-pin connector (DD) High-resolution or resolver applications (CE)		(M7)	
2090-CFBM7E7-CDAFxx	Drive-end (male) connector, extension (E7) (1)			
2090-CFBM7E7-CEAFxx	Motor-end SpeedTec DIN cable plug (M7)			
2090-CFBM4DF-CDAFxx	Drive-end flying-leads High-resolution or incremental applications		Threaded DIN (M4)	

⁽¹⁾ SpeedTec DIN connector (motor end) and male connector for extending SpeedTec or threaded DIN cable. Refer to SpeedTec DIN Continuous-flex Extension Cables on page 16.

IMPORTANT

Feedback cables with the CE designation, for example 2090-CFBM7DF-CEAAxx, are intended for high-resolution encoder or resolver applications and have fewer conductors than feedback cables with the CD designation, for example 2090-CFBM7DF-CDAFxx that are intended for high-resolution or incremental encoder applications.

TL-Series Low Inertia Motors

Cat. No.	Drive Compatibility	Feedback Type	Feedback Cable Cat. No.	IP Rating
TLY-Axxxx-H	2093-AC05-MPx or 2093-AMxx 2094-ACxx-Mxx-S or 2094-AMxx-S 2097-V3xPRx or 2097-V3xPRx-LM 2098-DSD-xxx	Incremental	2090-CFBM6DF-CBAAxx (flying lead) or 2090-CFBM6DD-CCAAxx (premolded connector)	— Shaft seal is optional:
	2071-Axx		2090-CFBM6DF-CBAAxx (flying lead)	IP54 without shaft seal
TLY-Axxxx-B	2093-AC05-MPx or 2093-AMxx 2097-V3xPRx or 2097-V3xPRx-LM	Multi-turn High Resolution	2090-CFBM6DF-CBAAxx (flying lead) or 2090-CFBM6DD-CCAAxx (premolded connector)	IP65 with shaft seal Cable connectors IP30
	2071-Axx	Absolute Encoder Feedback	2090-CFBM6DF-CBAAxx (flying lead)	
TL-Axxxx-B	2071-Axx		2090-DANFCT-Sxx ⁽¹⁾	

⁽¹⁾ Use when high-resolution absolute encoder feedback is not required. For high-resolution encoder applications, remove the drive-side connector and wire flying leads to the 2071-TBMF connector kit with customer-supplied 3.6V lithium battery.

TL-Series (200V-class) Motors	Power Cable Cat. No.	IP Rating
TLY-Axxxx-H	2090-CPBM6DF-16AAxx	Shaft seal is optional:
TLY-Axxxx-B	(power and brake) 2090-CPWM6DF-16AAxx	IP54 without shaft seal IP65 with shaft seal
	(power without brake)	Cable connectors IP30
TL-Axxxx-B	2090-DANPT-16Sxx	Capie Collifectors IF 50

TL-Series (200V-class) Motors	Brake Cable Cat. No.	IP Rating
TL-Axxxx-B motors	2090-DANBT-18Sxx	Shaft seal is optional: • IP54 without shaft seal • IP65 with shaft seal
		Cable connectors IP30

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on page 13. Cable length xx is in meters. Refer to Technical Specifications - 2090-Series Motor/Actuator Cables beginning on page 30. For N-Series retrofit cable information, refer to the Kinetix Rotary Motion Technical Data, publication GMC-TD001.

IMPORTANT

TL-Axxxx B motors have rectangular plastic connectors and are intended for use with Kinetix 3 (Bulletin 2071) servo drives. The TLY-Axxxx motors have circular plastic connectors and are intended for use with Bulletin 2093, 2094, 2097, and 2098 (200V-class) servo drives.

LDAT-Series Integrated Linear Thrusters

Actuator Cat. No.	Actuator Cat. No. Drive Compatibility		Feedback Cable Cat. No.	IP Rating
LDAT-Sxxxxxx-xDx (230V operation)	2198-Hxxx-ERS or 2198-Hxxx-ERS2 2097-V3xPRx	2090-CFBM7DF-CEAAxx or 2090-CFBM7DD-CEAAxx (standard, non-flex)		
LDAT-S <i>xxxxxx-x</i> D <i>x</i> (460V operation)	2198-Hxxx-ERS or 2198-Hxxx-ERS2 2198-Dxxx-ERS3 2097-V34PRx	– Absolute Linear Encoder Feedback	2090-CFBM7DF-CEAFxx 2090-CFBM7DD-CEAFxx (continuous-flex)	
LDAT-Sxxxxxxx-xBx (230V operation)	2093-AC05-MPx or 2093-AMxx 2094-ACxx-Mxx-S or 2094-AMxx-S 2097-V3xPRx 2098-DSD-xxx 2071-Axx	Incremental	2090-XXNFMF-Sxx (standard, non-flex)	IP30
LDAT-Sxxxxxx-xBx (460V operation)	2198-Dxxx-ERS3 2094-BCxx-Mxx-S or 2094-BMxx-S 2094-BCxx-Mxx-M or 2094-BMxx-M 2097-V34PRx 2098-DSD-HVxxx		2090-CFBM7DF-CDAFxx (continuous-flex)	

LDAT-Series (230V or 460V operation) Linear Thrusters	Power Cable Cat. No.	IP Rating	
LDAT-S031xxx, LDAT-S032xxx, LDAT-S033xxx			
LDAT-S051xxx, LDAT-S052xxx, LDAT-S053xxx, LDAT-S054xxx			
LDAT-S072xxx, LDAT-S073xxx, LDAT-S074xxx, LDAT-S076xxx-Exx	2090-CPWM7DF-16AAxx (standard, non-flex) 2090-CPWM7DF-16AFxx (continuous-flex)	IP30	
LDAT-S102xxx, LDAT-S103xxx, LDAT-S104xxx, LDAT-S106xxx-Exx	200 2		
LDAT-S152xxx, LDAT-S153xxx, LDAT-S154xxx, LDAT-S156xxx-Exx			
LDAT-S076xxx-Dxx			
LDAT-S106xxx-Dxx	2090-CPWM7DF-14AAxx (standard, non-flex) 2090-CPWM7DF-14AFxx (continuous-flex)		
LDAT-S156xxx-Dxx			

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on page 13. Cable length xx is in meters. Refer to Technical Specifications - 2090-Series Motor/Actuator Cables beginning on page 30.

TL-Series Electric Cylinders

Actuator Cat. No.	Drive Compatibility	Feedback Type	Motor Feedback Cable	IP Rating
TLAR-Axxxxx	2093-AC05-MPx or 2093-AMxx 2097-V3xPRx or 2097-V3xPRx-LM 2071-Axx	Multi-turn High Resolution Absolute Encoder Feedback	2090-CFBM6DF-CBAAxx (flying-lead) standard, non-flex	IP40 ⁽¹⁾

TL-Series (200V-class) Electric Cylinders	Motor Power Cable	IP Rating
TLAR-Axxxxx	2090-CPBM6DF-16AAxx (power and brake) standard, non-flex	IP40 ⁽¹⁾
	2090-CPWM6DF-16AAxx (power without brake) standard, non-flex	

 $^{(1) \}quad \text{Applies to complete unit, including rod-end seal and breather port.}$

For cable configuration illustrations and feature descriptions, by catalog number, refer to 2090-Series Motor/Actuator Cables Overview beginning on page 13. Cable length xx is in meters. Refer to Technical Specifications - 2090-Series Motor/Actuator Cables beginning on page 30.

Brake Cable Specifications

Brake Cables Cat. No.	Cable Type/ Jacket Color	Description	Wire Size AWG	Weight, approx kg/m (lb/ft)	Standard Cable Lengths m (ft)	
2090-DANBT-185xx	Standard (non-flex) cable, Industrial TPE, Black	Two conductor, 600V, 18 AWG, shielded cable for motor brake.	18	0.070 (0.047)	01 (3.2) 05 (16.4) 15 (49.2) 02 (6.5) 07 (22.9) 20 (65.6) 03 (9.8) 09 (29.5) 25 (82.0) 04 (13.1) 12 (39.4) 30 (98.4)	

Feedback Cable Specifications

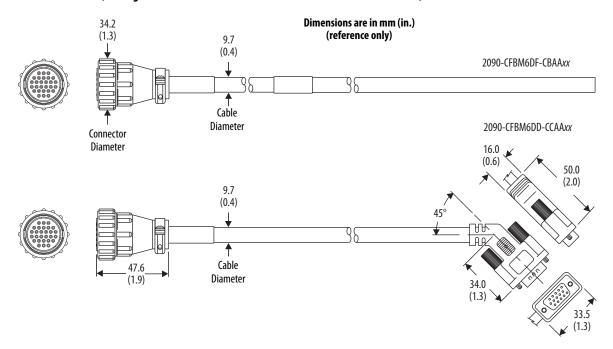
Feedback Cables ⁽¹⁾ ⁽²⁾ Cat. No.	Cable Type/ Jacket Color	Description	Wire Size AWG	Weight, approx kg/m (lb/ft)	Standard m (ft)	Standard Cable Lengths m (ft)	
2090-XXNFMF-Sxx	Standard (non-flex) cable, Industrial TPE, Black	Threaded DIN connector (motor end) to flying leads (drive end), 30V.	28 Feedback 16 Power, 5V 22 Power, 9V	0.120 (1.35)	01 (3.2) 02 (6.5)	07 (22.9) 09 (29.5)	25 (82.0) 30 (98.4)
2090-CFBM7DD-CEAAxx	Standard (non-flex) cable, Industrial TPE,	SpeedTec DIN connector (motor end) to premolded connector (drive end), 600V.	22 All	0.136 (0.092)	03 (9.8) 04 (13.1)	12 (39.4) 15 (49.2) 20 (65.6)	40 (131.2) 60 (196.8)
2090-CFBM7DF-CEAAxx	Green (DESINA, RAL 6018)	SpeedTec DIN connector (motor end) to flying leads (drive end), 600V.	conductors	0.130 (0.072)	05 (16.4)		90 (295.3)
2090-UXNFM-Sxx ⁽³⁾	Standard (non-flex) cable, Industrial TPE,	Flying-leads (motor end) to premolded connector (drive end), 30V.	28 Feedback 16 Power, 5V 22 Power, 9V	0.120 (1.35)	01 (3.2) 03 (9.8) 09 (29.5)	15 (49.2) 30 (98.4)	
2090-CFBM6DF-CBAAxx		Circular plastic connector (motor end) to flying leads (drive end), 300V.	28 Feedback 16 Power, 5V 22 BAT+		01 (3.2) 02 (6.5) 03 (9.8)	05 (16.4) 07 (22.9) 09 (29.5)	15 (49.2) 20 (65.6) 25 (82.0)
2090-CFBM6DD-CCAAxx	Black	Circular plastic connector (motor end) to premolded connector (drive end), 300V.	28 Feedback 16 Power, 5V				
2090-DANFCT-Sxx	-	Rectangular plastic connector (motor end) to premolded connector (drive end), 30V.	28 Feedback 16 Power, 5V 22 BAT+	0.130 (0.088)	04 (13.1)	12 (39.4)	30 (98.4)
2090-CFBM4DF-CDAFxx	Continuous-flex	Threaded DIN connector (motor end) to flying leads (drive end), 600V.	26 Feedback 16 Power, 5V	0.177 (0.119)	01 (3.2)	09 (29.5)	40 (131.2)
2090-CFBM7DF-CDAFxx	cable Industrial TPE, Green (DESINA, RAL 6018)	SpeedTec DIN connector (motor end) to flying	22 Power, 9V	Power, 9V	02 (6.5) 03 (9.8) 04 (13.1) 05 (16.4)	12 (39.4) 15 (49.2) 20 (65.6) 25 (82.0)	50 (164.0) 60 (196.8) 75 (264.0)
2090-CFBM7DF-CEAFxx		leads (drive end), 600V.	22 AII				
2090-CFBM7DD-CEAFxx		SpeedTec DIN connector (motor end) to premolded connector (drive end), 600V.	conductors	0.143 (0.096)	07 (22.9)	30 (98.4)	90 (295.3)

^{(1) 2090-}CFBM7xx-CEAxxx feedback cables are UL Listed, bulk cable, type PLTC-ER.

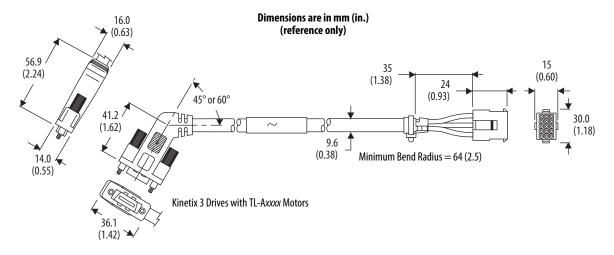
^{(2) 2090-}CFBM4DF-CDAxxx and 2090-CFBM7xx-CDAxxx feedback cables are UL Listed, bulk cable, type CM.

⁽³⁾ Use with 2090-KFBM4-CAAA (threaded) or 2090-KFBM7-CAAA (SpeedTec) DIN connector kit.

Feedback Cable Dimensions (catalog numbers 2090-CFBM6DF-CBAAxx and 2090-CFBM6DD-CCAAxx)



Feedback Cable Dimensions (catalog number 2090-DANFCT-Sxx)



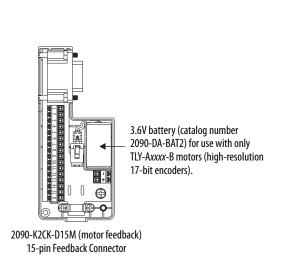
Low-profile Connector Kit Components

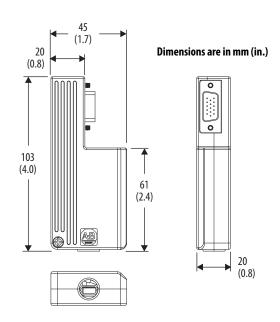
Low-profile connector kits are designed for use with the Kinetix 300/350, Kinetix 6000, Kinetix 6200/6500, Kinetix 2000, and Kinetix 7000 drives, and LIM modules. Use this table to identify the low-profile connector kit for your feedback or I/O connector.

IMPORTANT	The flying-lead compatible cables listed below require connector kits to complete feedback and I/O o	connections to the driv
Cat. No.	Description	Cable Compatibility
2090-K2CK-D15M	Low-profile connector kit for motor feedback (15-pin, male, D-sub). Use with any Kinetix 2000 IAM/AM module or Kinetix 300/350 drive and compatible motors with incremental or high-resolution feedback. Does not include 3.6V battery (catalog number 2090-DA-BAT2) required for use with TLY-Axxxx-B high-resolution motors and 17-bit encoders.	2090-XXNFMF-Sxx 2090-CFBM4DF-CDAFxx 2090-CFBM7DF-CEAAxx 2090-CFBM7DF-CEAFxx 2090-CFBM7DF-CDAFxx 2090-CFBM6DF-CBAAxx
2090-K2CK-COMBO	Low-profile connector kit for motor feedback (15-pin, male, D-sub) and I/O (44-pin, male, D-sub). Use with any Kinetix 2000 IAM/AM module and compatible motors with incremental or high-resolution feedback. Does not include 3.6V battery (catalog number 2090-DA-BAT2) required for use with TLY-Axxxx-B high-resolution motors and 17-bit encoders. The 2090-K2CK-COMBO kit, mounted on the Kinetix 2000 (IAM/AM) drive, fits in a standard 10 in. enclosure.	
2090-K6CK-D15M	Low-profile connector kit for motor feedback (15-pin, male, D-sub). Use with any Kinetix 6000, Kinetix 6200/6500, or Kinetix 7000 drive and compatible motors with incremental or high-resolution feedback.	
	Low-profile connector kit for motor feedback (15-pin, male, D-sub). Use with any Kinetix 6000 IAM/AM module and MPL-Bxxxx-R or MPM-A/Bxxxxx-2 (resolver feedback) motors.	2090-CFBM7DF-CEAAxx 2090-CFBM7DF-CEAFxx
2090-K6CK-D15F	Low-profile connector kit for auxiliary feedback (15-pin, female, D-sub). Use with any Kinetix 6000 IAM/AM module or Kinetix 7000 drive auxiliary feedback application.	Customer supplied
2090-K6CK-D26M	Low-profile connector kit for I/O (26-pin, male, D-sub). For use with any Kinetix 6000 IAM/AM module, Kinetix 7000 drive, or 2094-AL09 and 2094-BL02 LIM module.	
2090-K6CK-D44M	Low-profile connector kit for I/O, safety, and auxiliary feedback (44-pin, male, D-sub). For use with any Kinetix 6200 or Kinetix 6500 control module.	
2090-K6CK-D44S0	Low-profile connector kit for I/O and cascading safe torque-off signals (44-pin, male, D-sub). For use with any Kinetix 6200 or Kinetix 6500 (safe torque-off, -SO control module). Refer to Kinetix 6200 and Kinetix 6500 Safe-off Components on page 93 for example diagrams.	2090-CS0DSDS-AAxx

Dimensions - Low-profile Connector Kits

Catalog Number 2090-K2CK-D15M



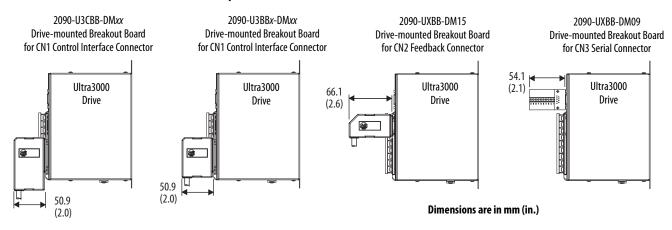


Drive-mounted Breakout Board Kits

Use these examples to identify the best solution for wiring your flying-lead control interface, motor feedback, and serial cables to Ultra3000 and Kinetix 3 drives.

In this example, the Ultra3000 drives are shown with drive-mounted breakout board kits (catalog number 2090-Uxxx-DMxx). Drive-mounted breakout board kits are available for the control interface (CN1), motor feedback (CN2), and serial interface (CN3) connectors. Refer to Drive-mounted Breakout Board Components on page 72 for more information.

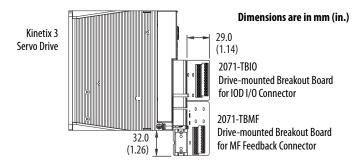
Ultra3000 Drive-mounted Breakout Board Examples



TIP The 2090-UXBB-DM15 (feedback) kit is also compatible with the Kinetix 2000 IAM/AM, Kinetix 6000 IAM/AM, and Kinetix 7000 drives (MF feedback connectors only).

In this example, the Kinetix 3 drives are shown with drive-mounted breakout boards (catalog numbers 2071-TBMF and 2071-TBIO). Use the 2071-TBMF breakout board with 2090-CFBM6DF-CBAAxx feedback cables or when your motor or actuator has high-resolution encoder feedback. Use the 2071-TBIO breakout board for making flying-lead cable connections to twenty-four of the most commonly used terminals in the 50-pin IOD connector. Refer to Drive-mounted Breakout Board Components on page 72 for more information.

Kinetix 3 Drive-mounted Breakout Board Examples



Panel-mounted Breakout Board Components

Breakout boards, cables, and kits (designed for DIN rail mounting on the panel) and for use with Kinetix drives as specified in the description are shown below. These breakout board components can be ordered separately, or as a kit containing both terminal block and cable.

Panel-mounted Breakout Board Kits

Cat. No.	Description	Cable Compatibility
2090-UXBK-D15 <i>xx</i>	DIN rail terminal block (catalog number 2090-UxBB-Dxx) and cable (catalog number 2090-UxBC-Dxxxx) for motor feedback connector (15-pin, male, D-sub). Use with any Kinetix 300/350, Kinetix 2000, Kinetix 6000, Kinetix 6200/6500, or Kinetix 7000 drives (MF connector) or Ultra3000 drives (CN2 connector) for motor feedback connections.	2090-XXNFMF-Sxx 2090-CFBM4DF-CDAFxx 2090-CFBM7DF-CEAAxx 2090-CFBM7DF-CEAFxx 2090-CFBM6DF-CBAAxx
	Terminal block and cable for motor feedback connector (15-pin, male, D-sub). Use with Kinetix 6000 drives, MPL-BxxxxR, and MPM-A/Bxxxxx-2 (resolver feedback) motors.	2090-CFBM7DF-CEAAxx
2090-U3BK-D44 <i>xx</i>	Terminal block and cable for control interface connector (44-pin, male, D-sub). Use with Ultra3000 drives (CN1 connector) or Kinetix 2000 drives (IOD/AF connector).	Customer Supplied

Panel-mounted Breakout Boards

Cat. No.	Description
2090-UXBB-D15	15-pin terminal block with D-sub connector. Use with any Kinetix 300/350, Kinetix 2000, Kinetix 6000, Kinetix 6200/6500, or Kinetix 7000 drives (MF connector) or Ultra3000 drives (CN2 connector) for motor feedback connections.
2090-U3BB-D44	44-pin terminal block with D-sub connector. Use with Ultra3000 drives (CN1 connector) or Kinetix 2000 drives (IOD/AF connector) for control interface connections.

IMPORTANT	The flying-lead compatible cables listed above require either 2090-UXBB-DM15 (drive-mounted) or 2090-UXBB-D15 (panel-
	mounted) breakout board connector kits to complete feedback and I/O connections to the drive.

Panel-mounted Breakout Cables

Cat. No.	Description
2090-UXBC-D15 <i>xx</i>	15-pin cable with D-sub connector. Use with any Kinetix 300/350, Kinetix 2000, Kinetix 6000, Kinetix 6200/6500, or Kinetix 7000 drives (MF connector) or Ultra3000 drives (CN2 connector) for motor feedback connections.
2090-U3BC-D44xx ⁽¹⁾	44-pin cable with D-sub connector. Use with Ultra3000 drives (CN1 connector) or Kinetix 2000 drives (IOD/AF connector) for control interface connections.

⁽¹⁾ This cable does not carry the unbuffered motor encoder signals (CN1 pins 10...15). Contact your Rockwell Automation sales representative if these signals are required for your application.